

Challenges
from my perspective

over den Embeddede Verden

Kim Guldstrand Larsen

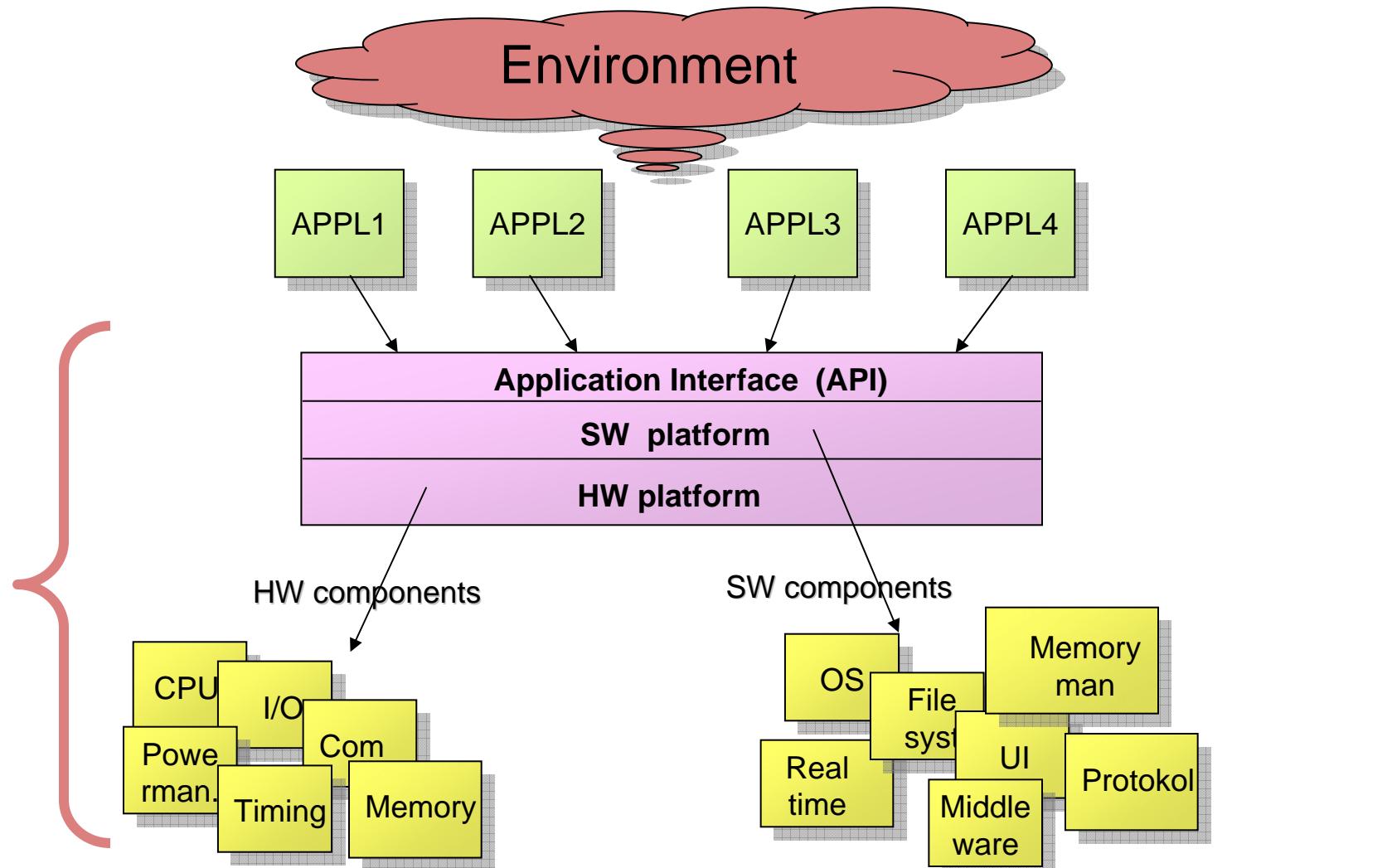
Center for Embedded Systems
Department of Computer Science
Aalborg University
DENMARK



Center for Indlejrede Software Systemer

▪ Embedded Systems – Levels

Ingeniøren
ELEKTRONIK-08

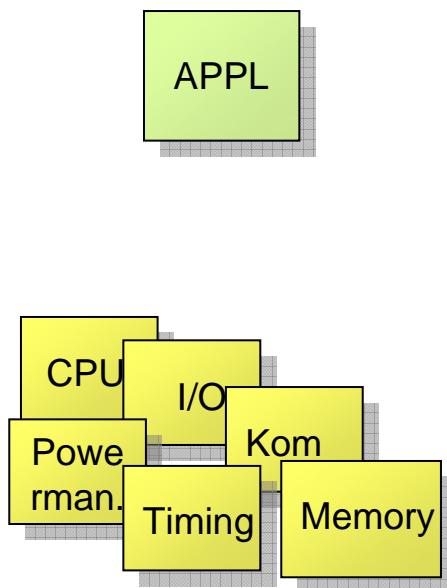
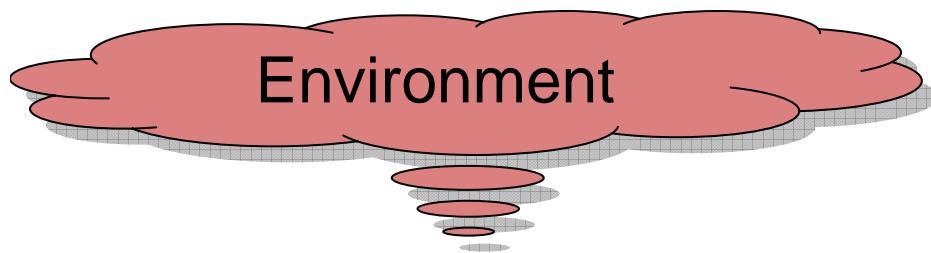




Embedded Systems – Formalisms

Ingeniøren

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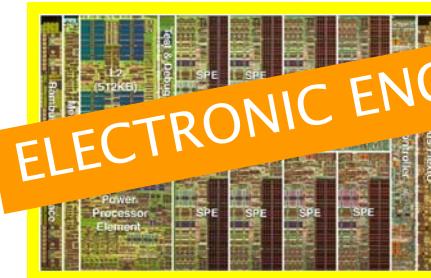


$$u(t) = K_p e(t) + K_i \int_0^t e(\tau) d\tau + K_d \frac{de}{dt}$$

```
private void handleBrick() {  
    Sensors.synchronizedReadSensors();  
    int input = (Sensors.getBufferedSensor(0) + Sensors  
        .getBufferedSensor(1)) >> 1;
```

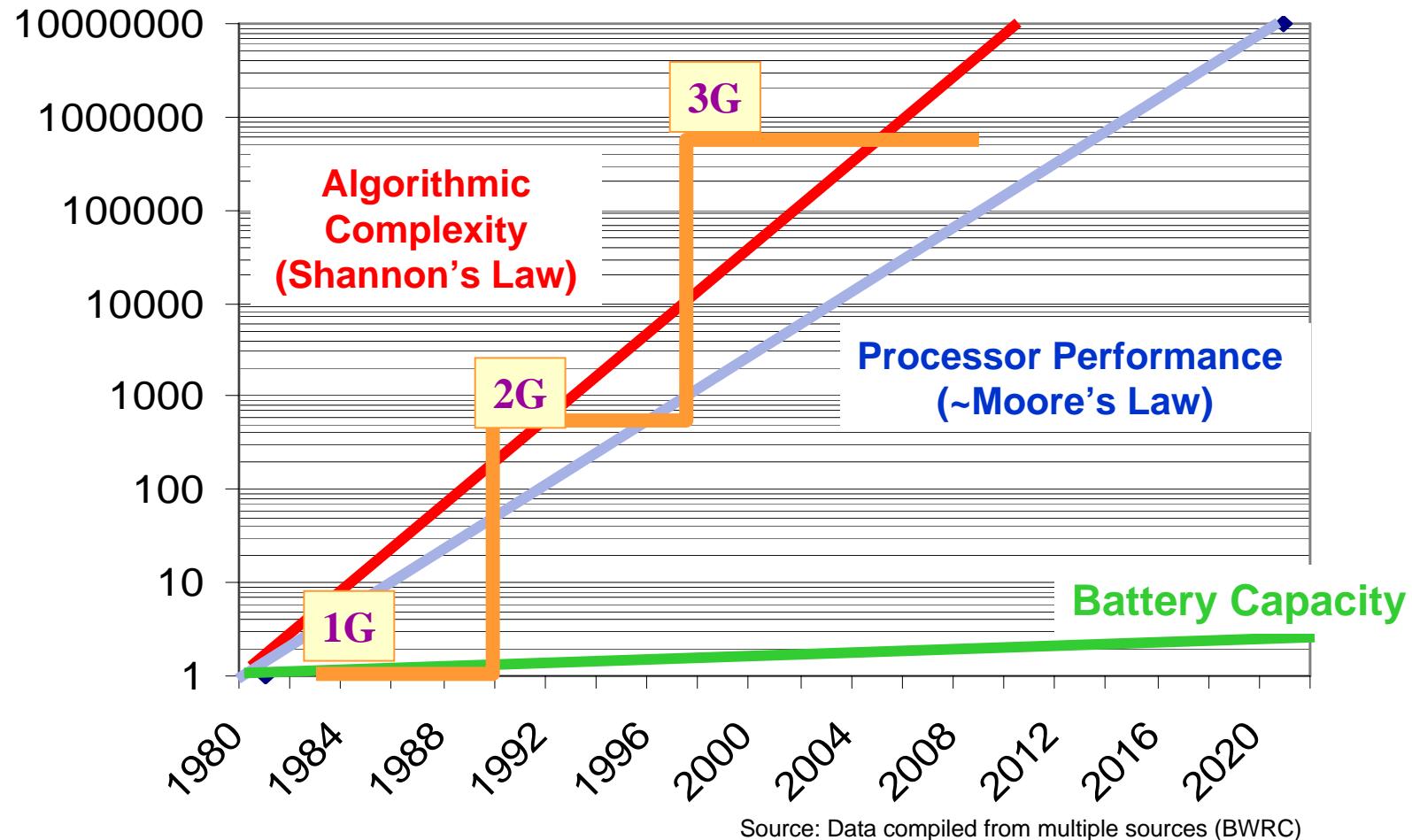
```
    if (awaitingBrick) {  
        if (input > lastRead) {  
            lastRead = input;  
        } else if ((lastRead - input) >= TRESHOLD) {  
            awaitingBrick = false;  
            if (lastRead > BRICKV  
                return true;  
        }  
    }  
    brickFound(l
```

COMPUTER SCIENCE

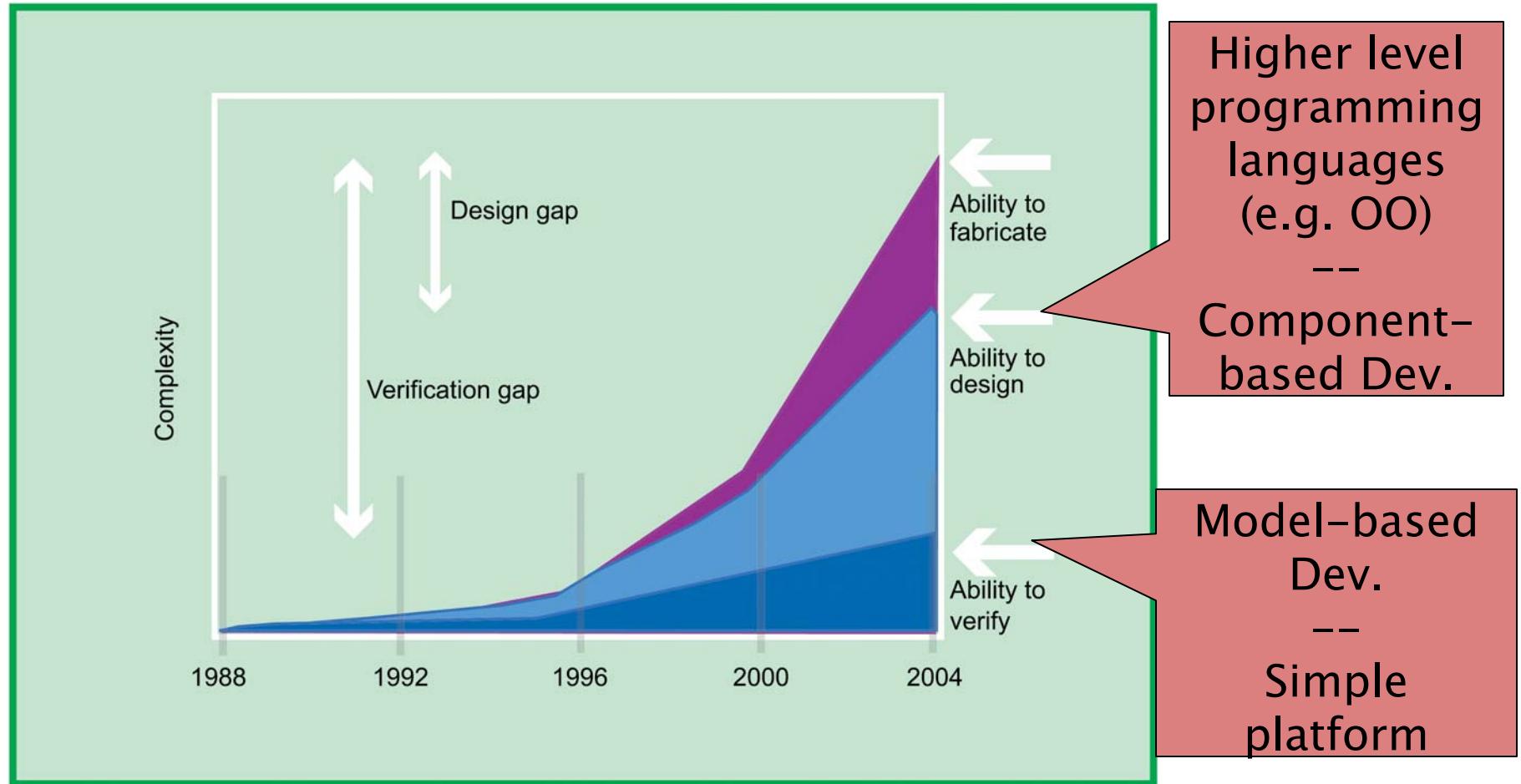


ELECTRONIC ENGINEERING

Technology Gaps



Design & Verification Gap

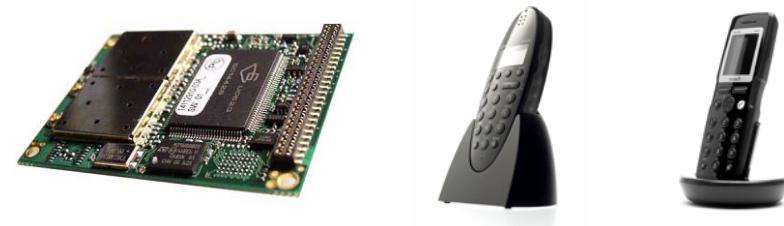


Brian Bailey, Chief Technologist, Design Verification and Test Division, Mentor Graphics Corp.

Java Object – Regional IKT Korridor

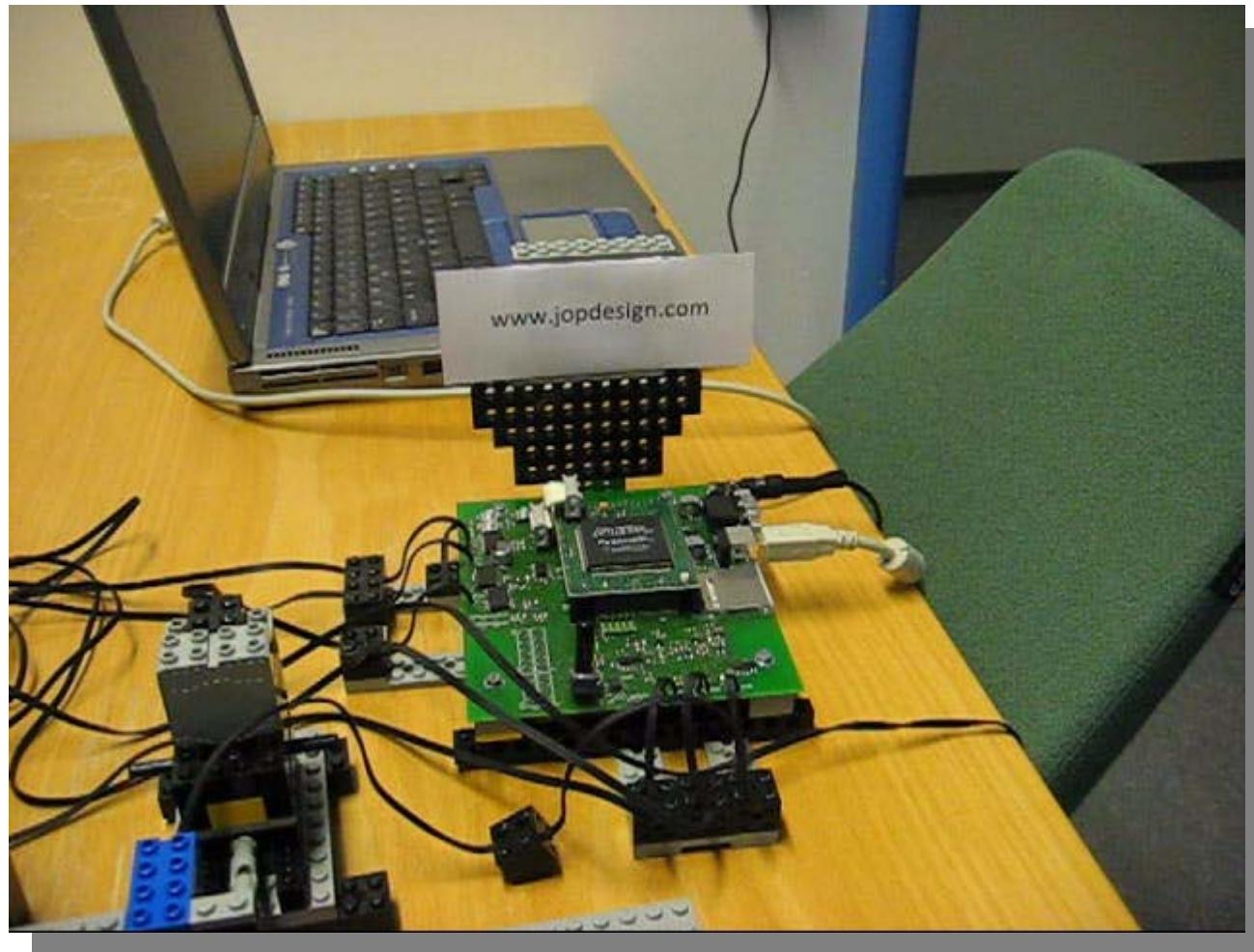
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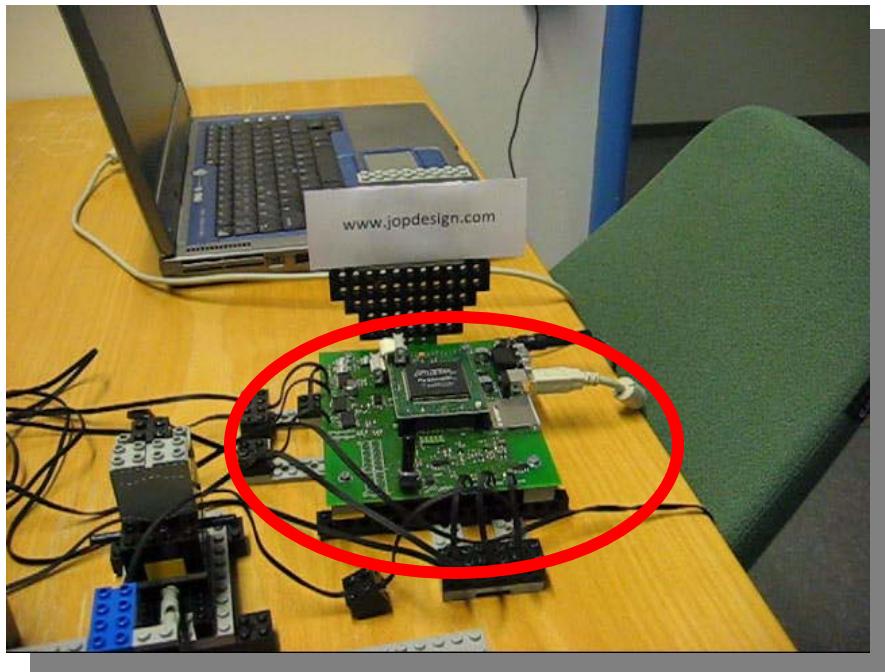
- Productivity of a programmer is increased with up to 700 % by changing from C/C++ to Java !
- Number of well-educated Java programmers increasing !
- Java for hard real-time systems ?
- Java and C/Assembler legacy code ?
- Emerging new profiles and hardware implementations !
- Eclipse framework !
- Center for Embedded Software Systems
- Vitus Bering Denmark
- Polycom (Kirk Telecom A/S)
- Wirtek A/S
- Mechatronic Brick ApS
- Aalborg Industries A/S
- Prevas A/S
- Teknologisk Institut
- Tekkva Consult (project coordinator).



❖ Real-Time Sorting

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- JOP (Java Optimized Processor)
- Native execution of Java Bytecode
- Bytecode implemented in Microcode
- Avoid unpredictable data-cache
- Time predictable
- Developed new method and stack cache
- Implemented in FPGA

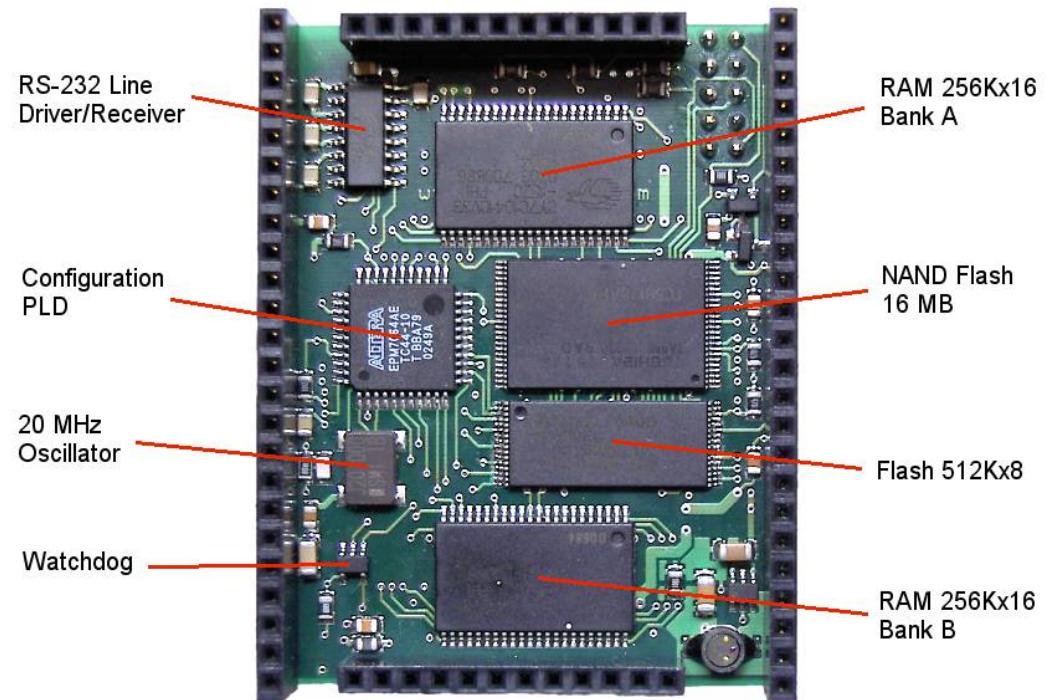
Java Optimizing Processor

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FPGA



Martin Schöberl
University of Tech., Vienna

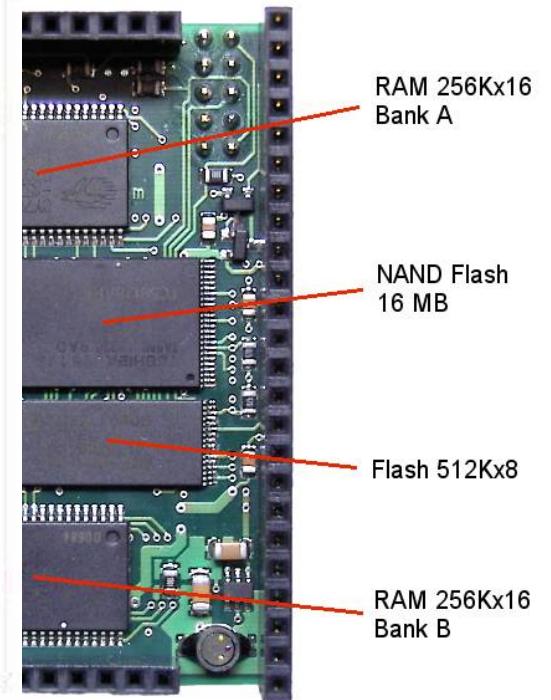
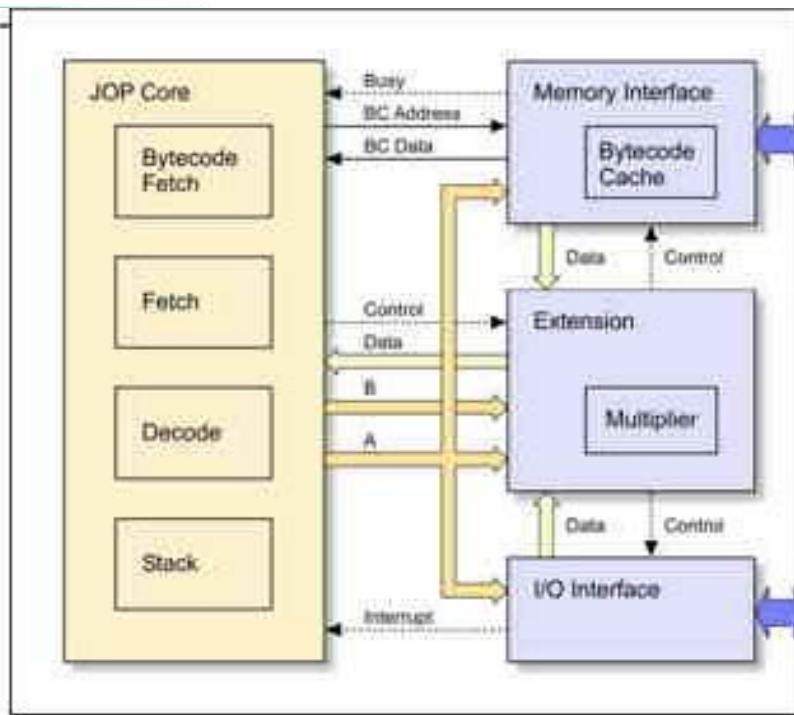


JOP Block Diagram

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FPGA

3–4 different FPGAs
6 different boards



⊕ Safety Critical Java

Tasks

```
public static void main(String[] args) {
    new SporadicPushMotor(
        new SporadicParameters(4, 4000, 60), 0);
    new SporadicPushMotor(
        new SporadicParameters(2, 4000, 60), 1);

    PeriodicMotorSpooler motorSpooler =
        new PeriodicMotorSpooler(
            new PeriodicParameters(4000));

    new PeriodicReadSensor(
        new PeriodicParameters(2000), motorSpooler);

    RealtimeSystem.start();
}
```

Min interarrival

Deadline



⊕ Byte code – Micro code

```
protected boolean run()
    if i<5 {
        i = i + 4;
    } else {
        i = i * 4;
    }
    return true;
}
```

Method: run ()Z
0: aload_0
1: getfield
4: ifeq -> 20
7: aload_0
8: dup
9: getfield
12: iconst_1
13: iadd
14: putfield
17: goto -> 30
20: aload_0
21: dup
22: getfield
25: iconst_1
26: isub
27: putfield
30: iconst_1
31: ireturn

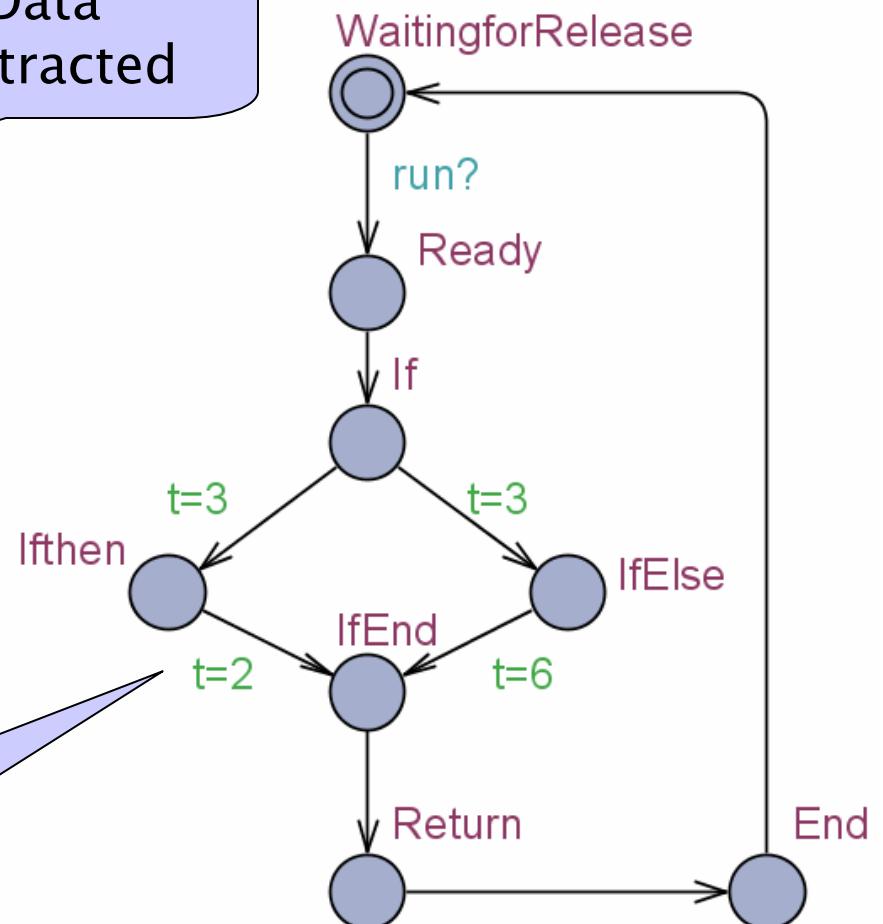


Byte code – Timed Automata

```
protected boolean run()  
{  
    if i<5 {  
        i = i + 4;  
    } else {  
        i = i * 4;  
    }  
    return true;  
}
```

Data abstracted

Timing = WCET
from microcode





SARTS – from Safety Critical Java

```
public static void main(String[] args) {  
    new SporadicPushMotor(  
        new SporadicParameters(4, 4000, 60), 0);  
    new SporadicPushMotor(  
        new SporadicParameters(4, 4000, 60), 1);  
  
    PeriodicMotorSpooler motorSpooler =  
        new PeriodicMotorSpooler(  
            new PeriodicMotor(  
                new SporadicPushMotor(  
                    new SporadicParameters(4, 4000, 60), 0),  
                    new SporadicPushMotor(  
                        new SporadicParameters(4, 4000, 60), 1)),  
                new SporadicPushMotor(  
                    new SporadicParameters(4, 4000, 60), 2));  
  
    new PeriodicReadSensor(  
        new PeriodicParameters(1000),  
        Sensors.getBufferedSensor(0));  
  
    RealtimeSystem.start();  
}
```

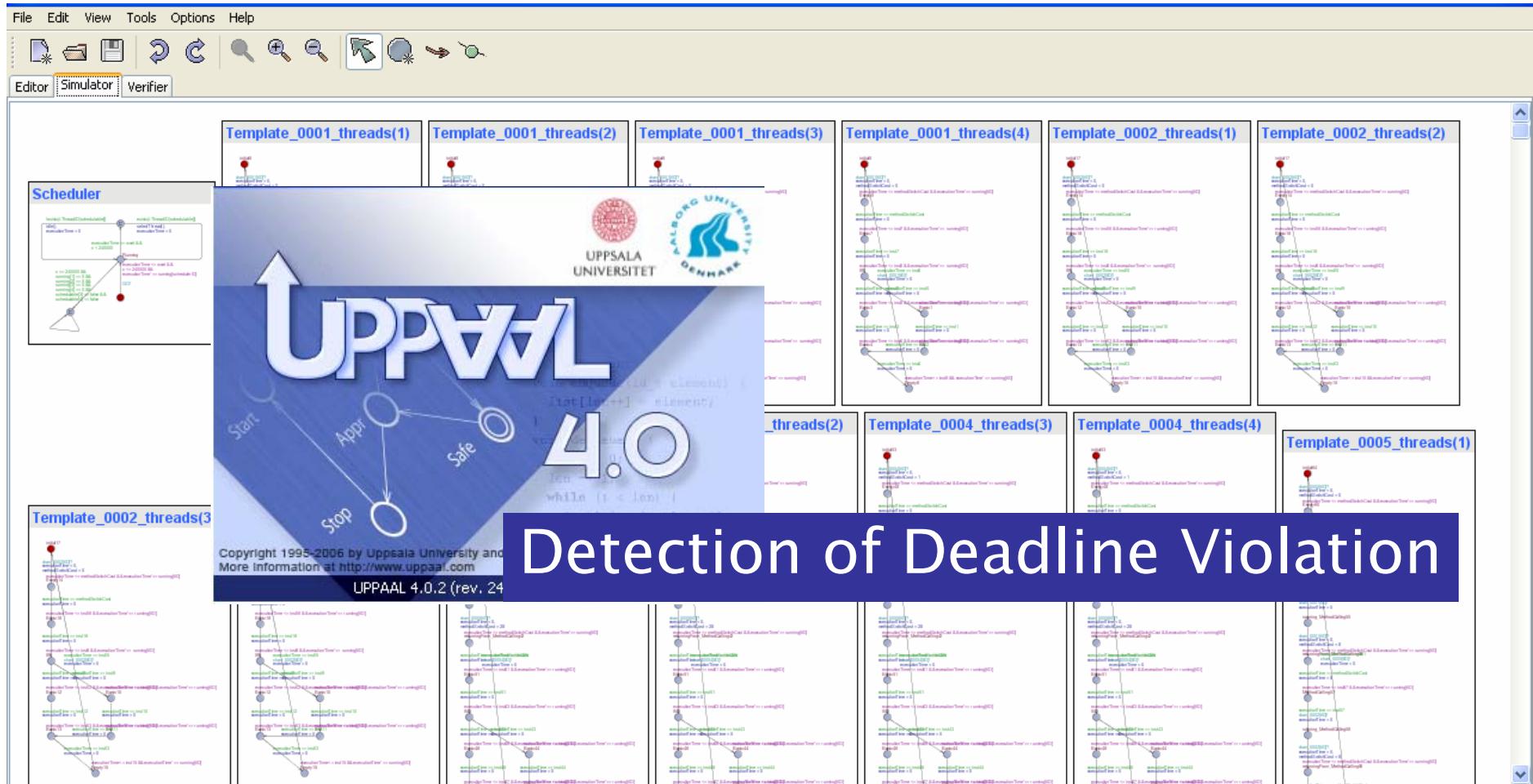
TASKS

```
private void handleBrick() {  
    Sensors.synchronizedReadSensors();  
    int input = (Sensors.getBufferedSensor(0) + Sensors.  
        getBufferedSensor(1)) >> 1;  
  
    if (awaitingBrick) {  
        if (input > lastRead) {  
            lastRead = input;  
        } else if ((lastRead - input) >= TRESHOLD) {  
            awaitingBrick = false;  
            if (lastRead > BRICK_DETECTED) {  
                brickFound(lastRead);  
            }  
        }  
    }  
}
```

METHODS

SARTS - to Timed Automata

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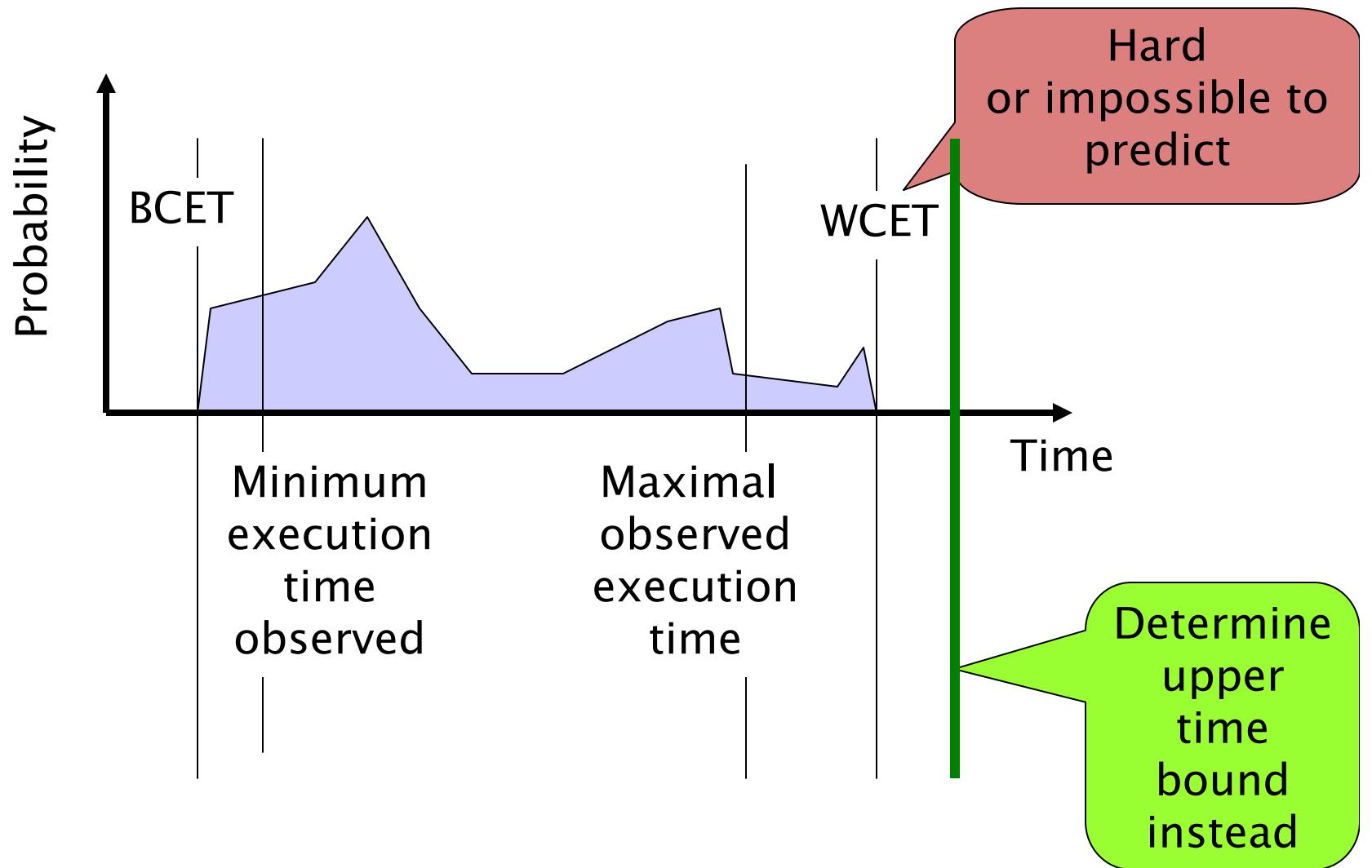


18 methods + 4 tasks = 76 components





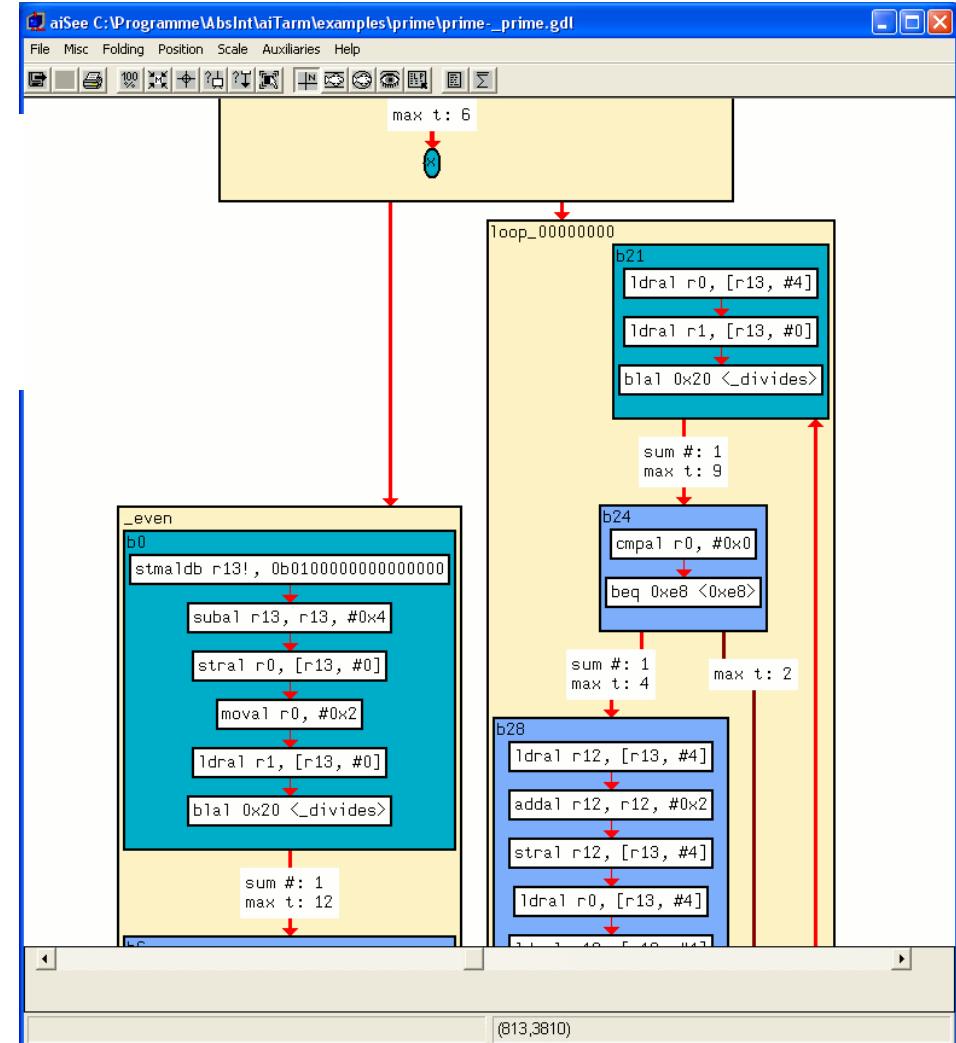
WCET: Worst Case Execution Time



• AbsInt - WCET state-of-the-art

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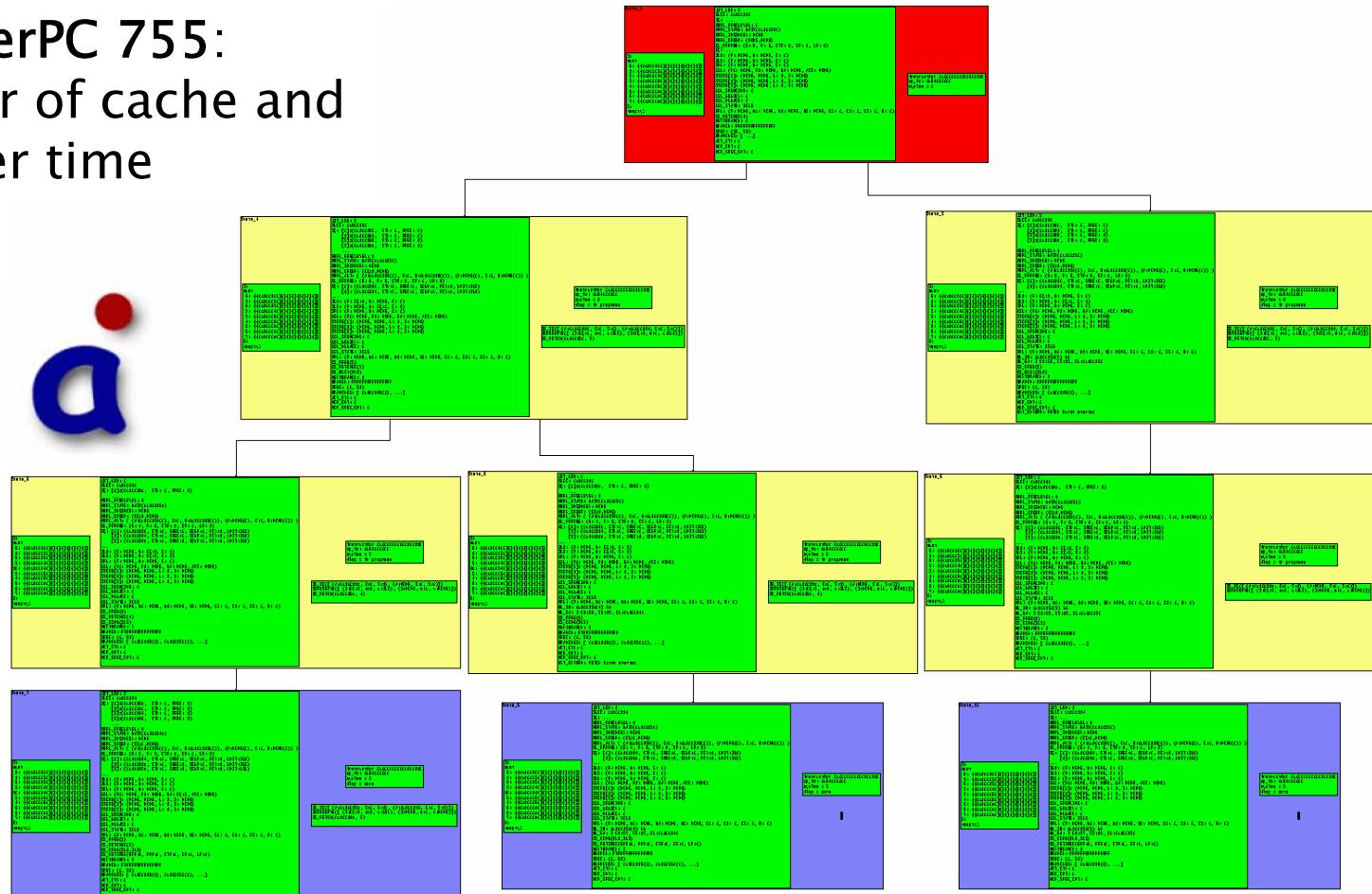
aiT for ARM7 TDMI
max t describes the maximum
execution time of the
basic block



• AbsInt - WCET state-of-the-art

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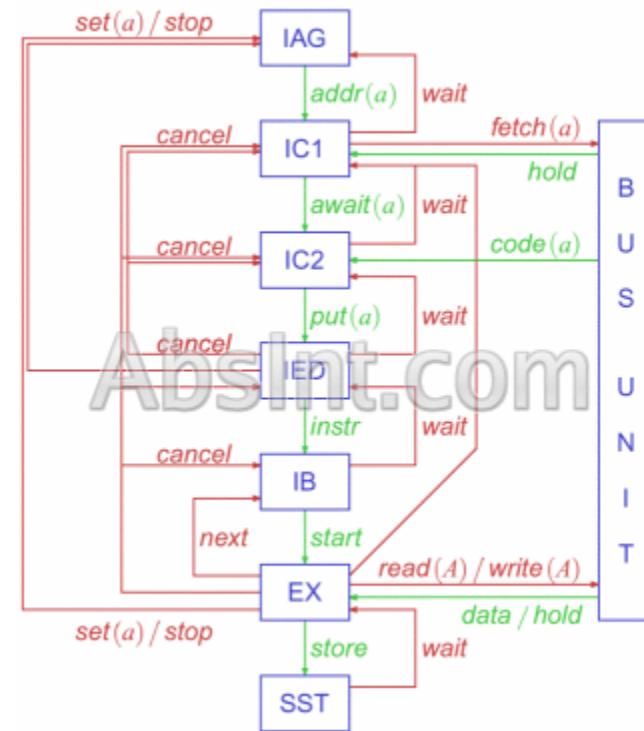
aiT for PowerPC 755:
the behavior of cache and
pipeline over time



AbsInt - WCET state-of-the-art

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aiT for ColdFire 5307:
Map of the formal pipeline model
used for timing validation.



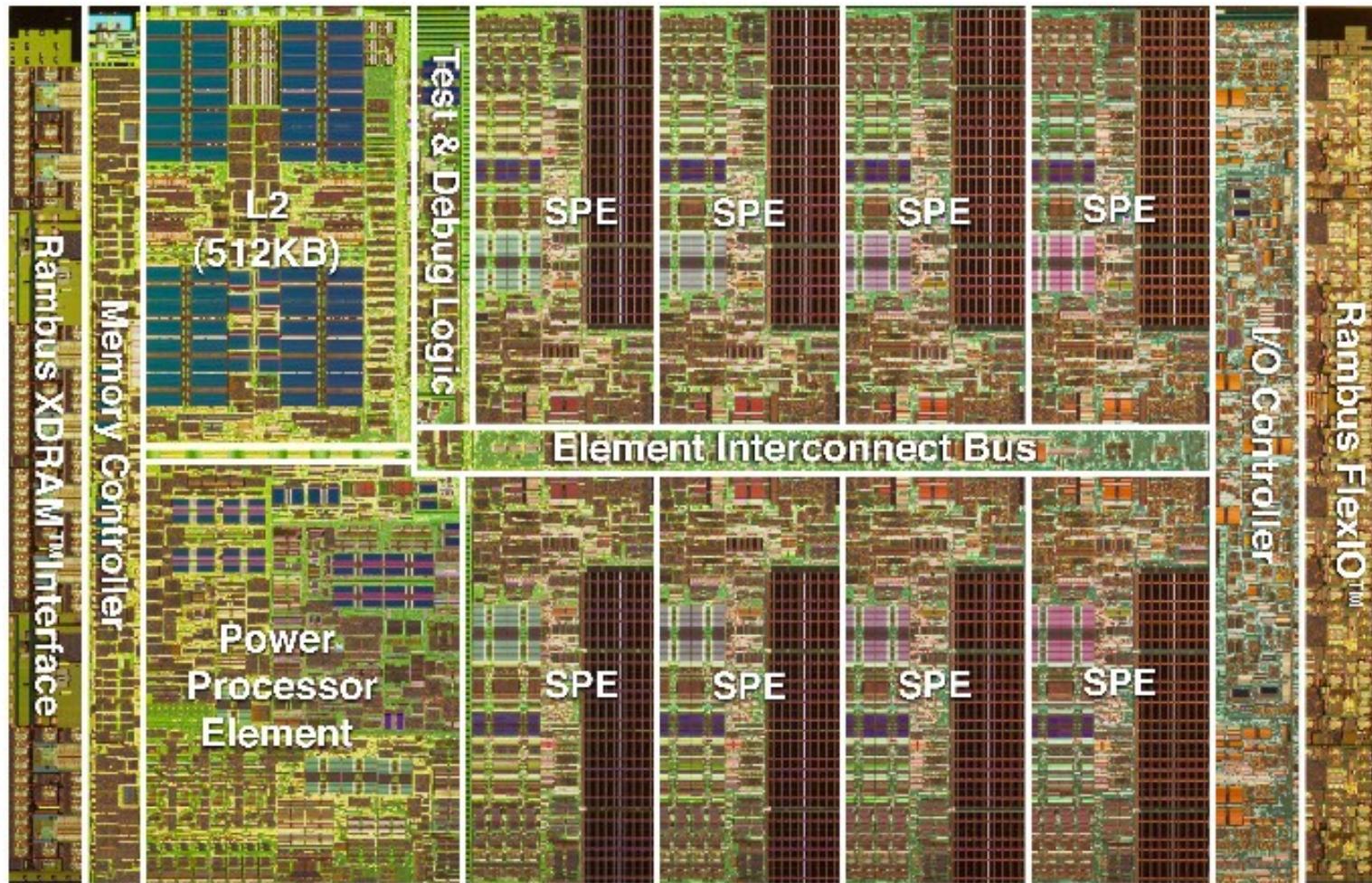
AbsInt - WCET state-of-the-art

Experiment	Target Processor	Average WCET overestimation	Other Methods
Review by Airbus	MPC7E	<25%	"useless"
Review on Voi code		16%	212%
Tests with ASCET	ST10	3%	-
aIT vs ARMulator			-
WCET Tool Challenge	C16x, ARM7, MPC565	7-8%	81%

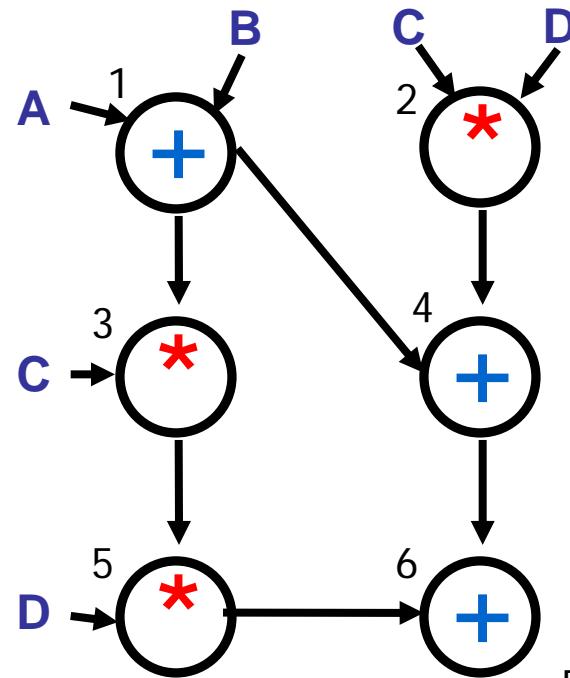
STATIC ANALYSIS

INTEGER LINEAR PROGRAMMING

The CELL processor



Optimal Scheduling - Time



Compute :
 $(D * (C * (A + B)) + ((A + B) + (C * D)))$
using 2 processors

P1 (fast)

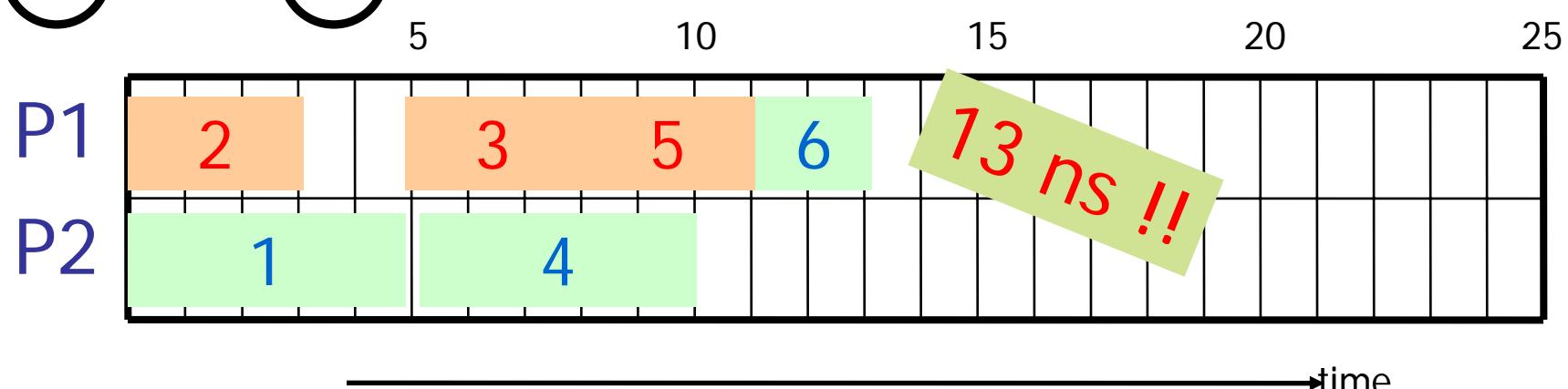


+	2ns
*	3ns

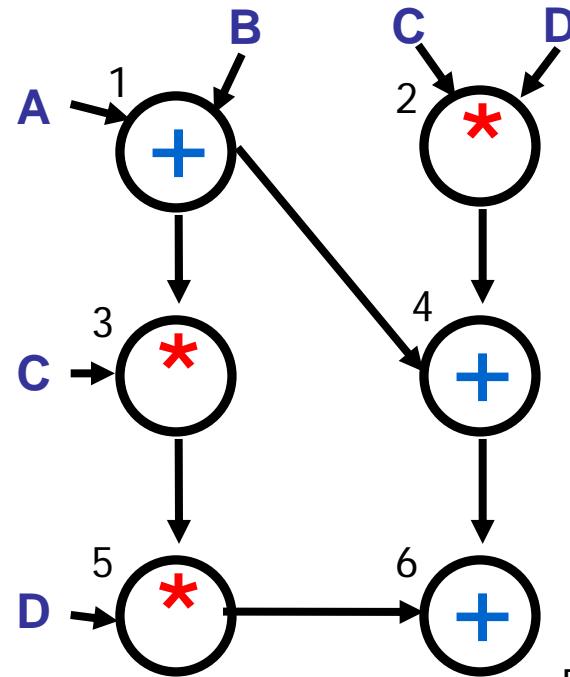
P2 (slow)



+	5ns
*	7ns



Optimal Scheduling - Time



Compute :
 $(D * (C * (A + B)) + ((A + B) + (C * D)))$
using 2 processors

P1 (fast)

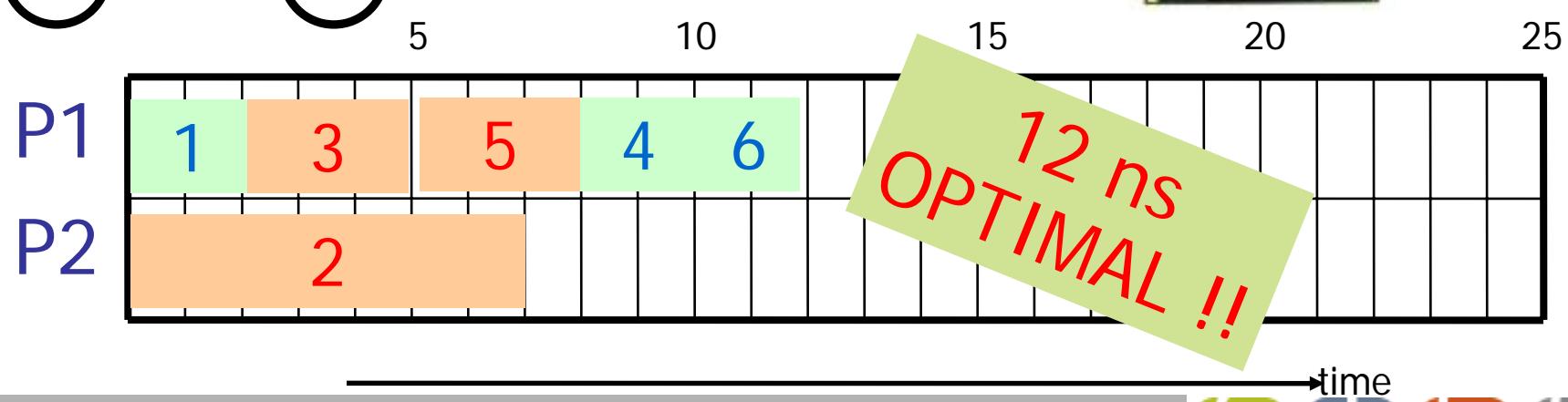


+	2ns
*	3ns

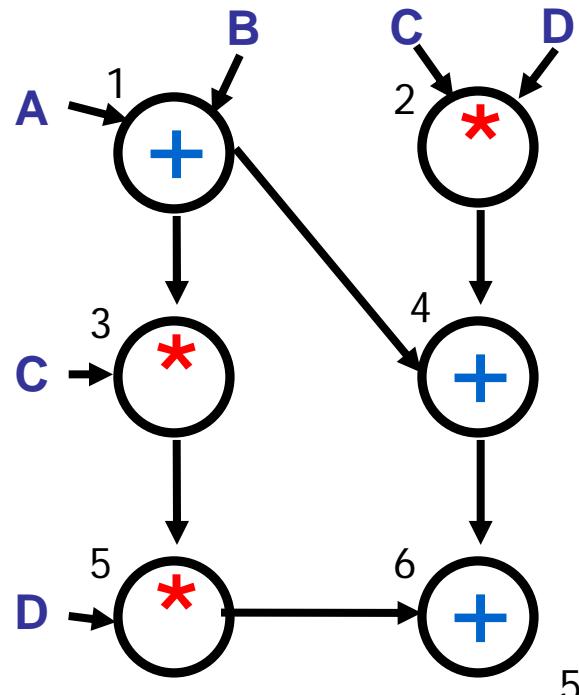
P2 (slow)



+	5ns
*	7ns

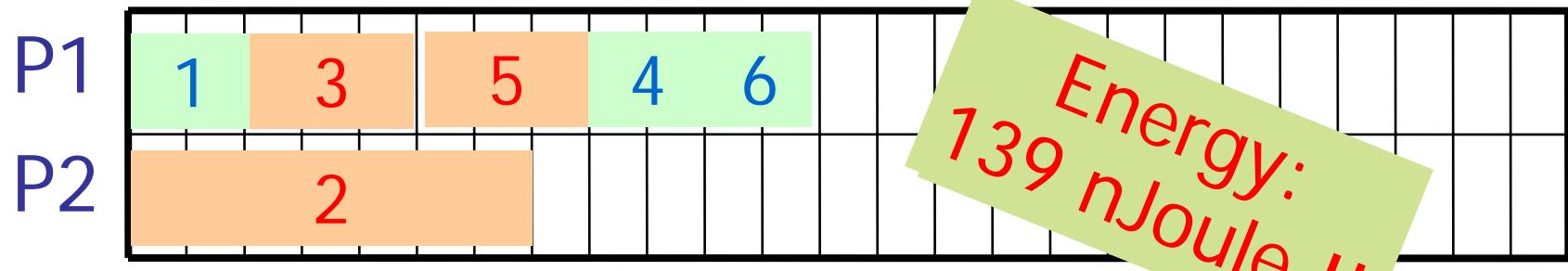
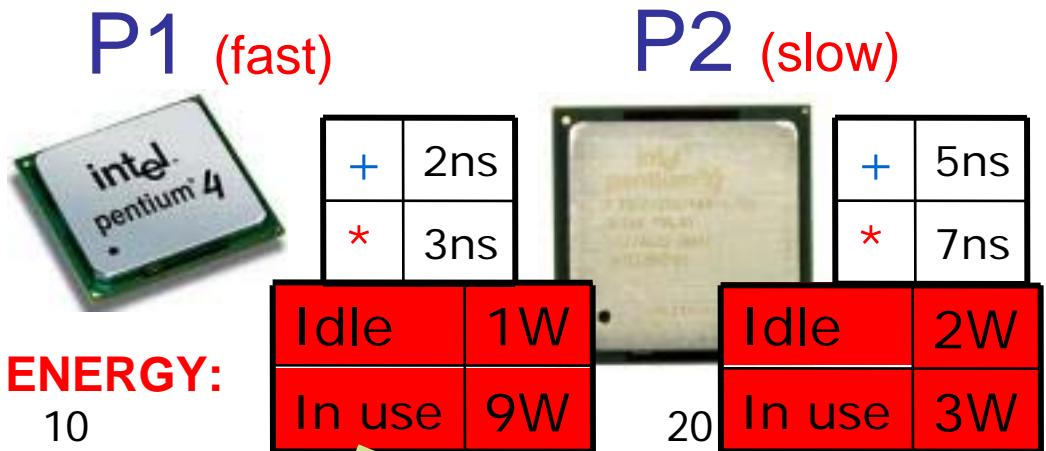


Optimal Scheduling - Power

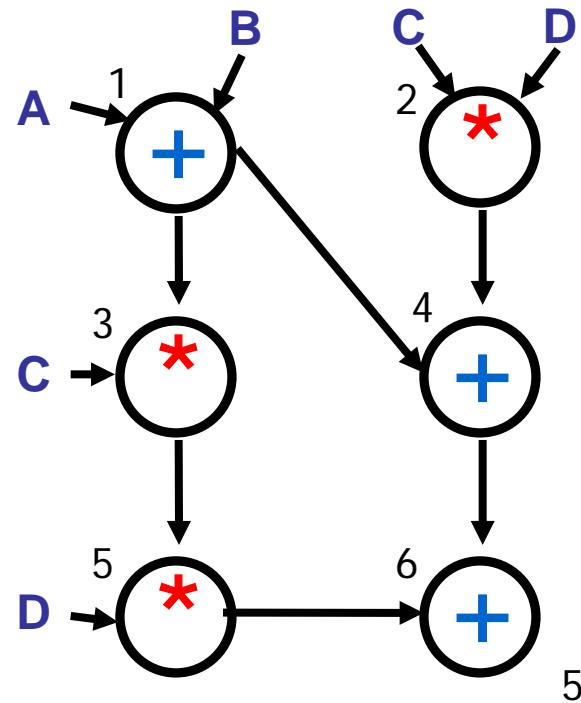


Compute :
$$(D * (C * (A + B)) + ((A + B) + (C * D)))$$

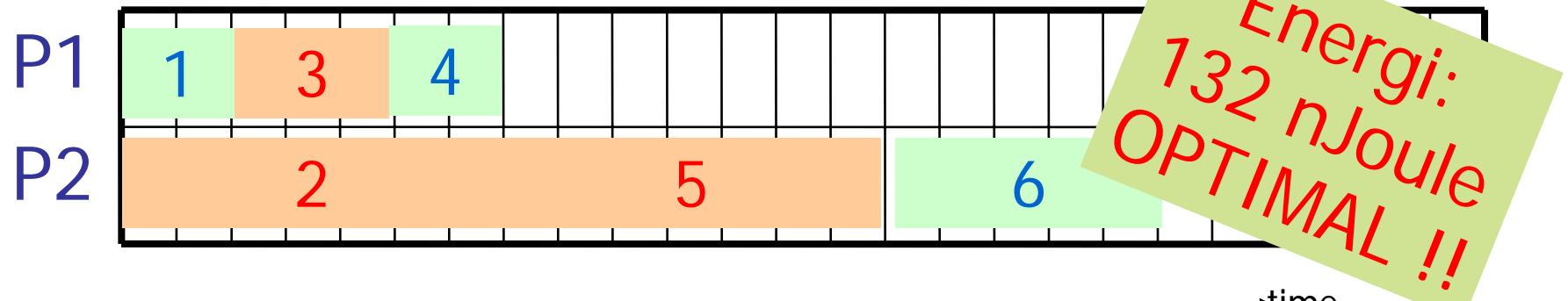
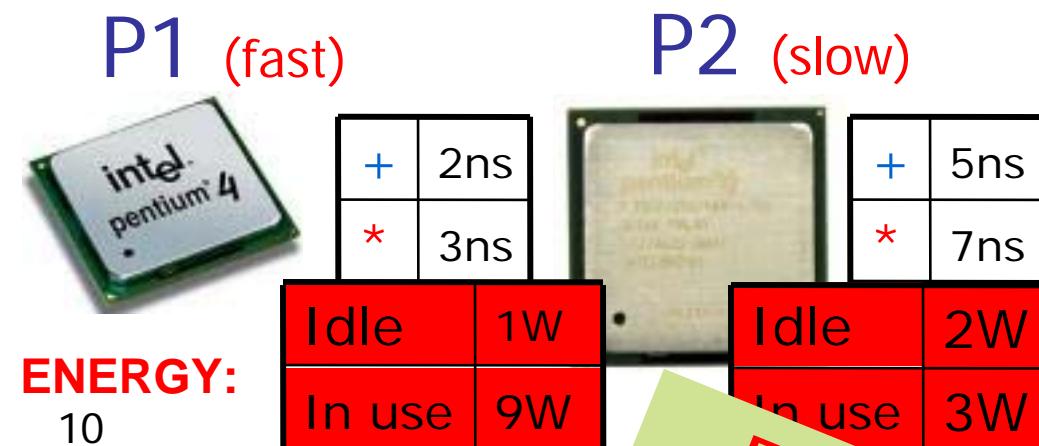
using 2 processors



Optimal Scheduling - Power



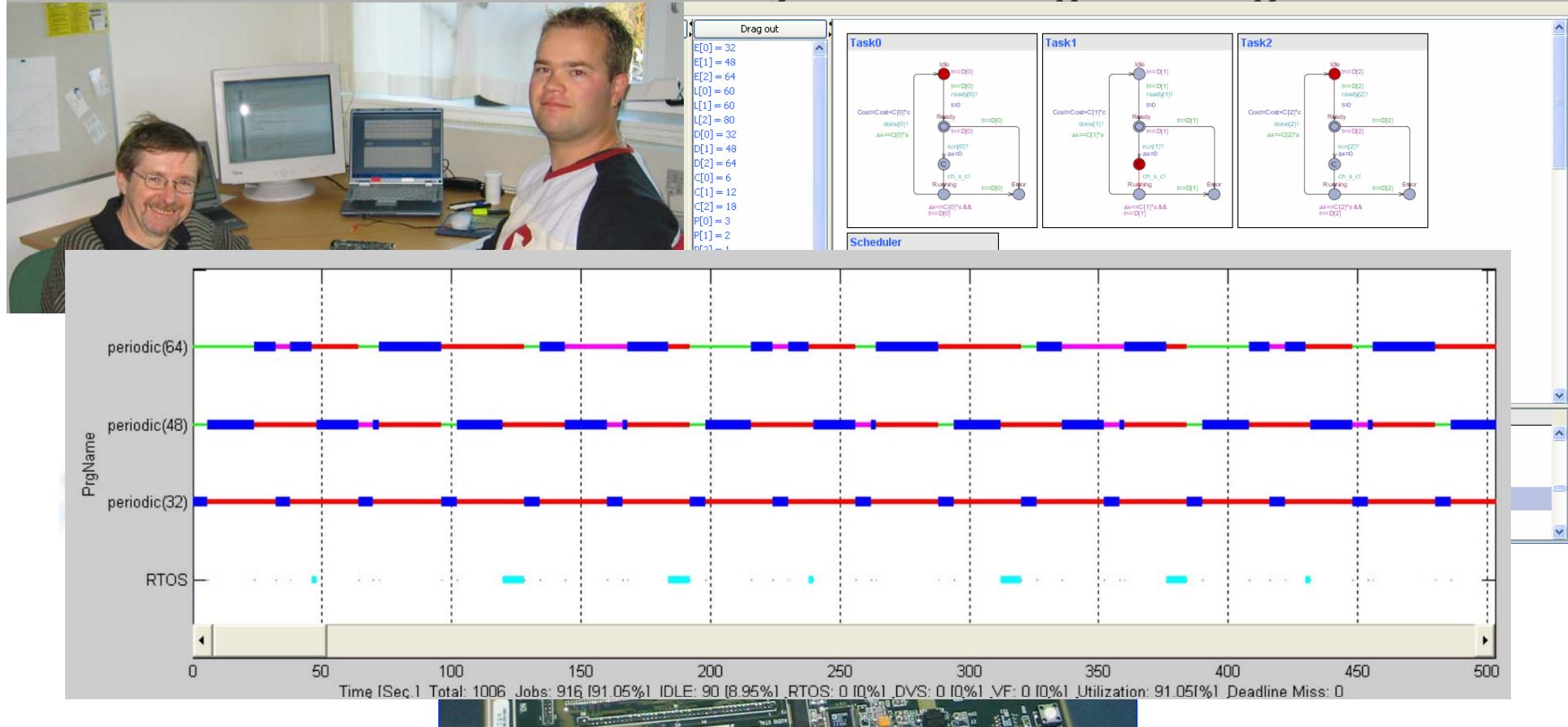
Compute :
 $(D * (C * (A + B)) + ((A + B) + (C * D)))$
using 2 processors



Power Management

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Dynamic Voltage Scaling



Dynamically lower voltage supply (frequency)
to utilize free CPU time [A. Skou & A. Brødløs]



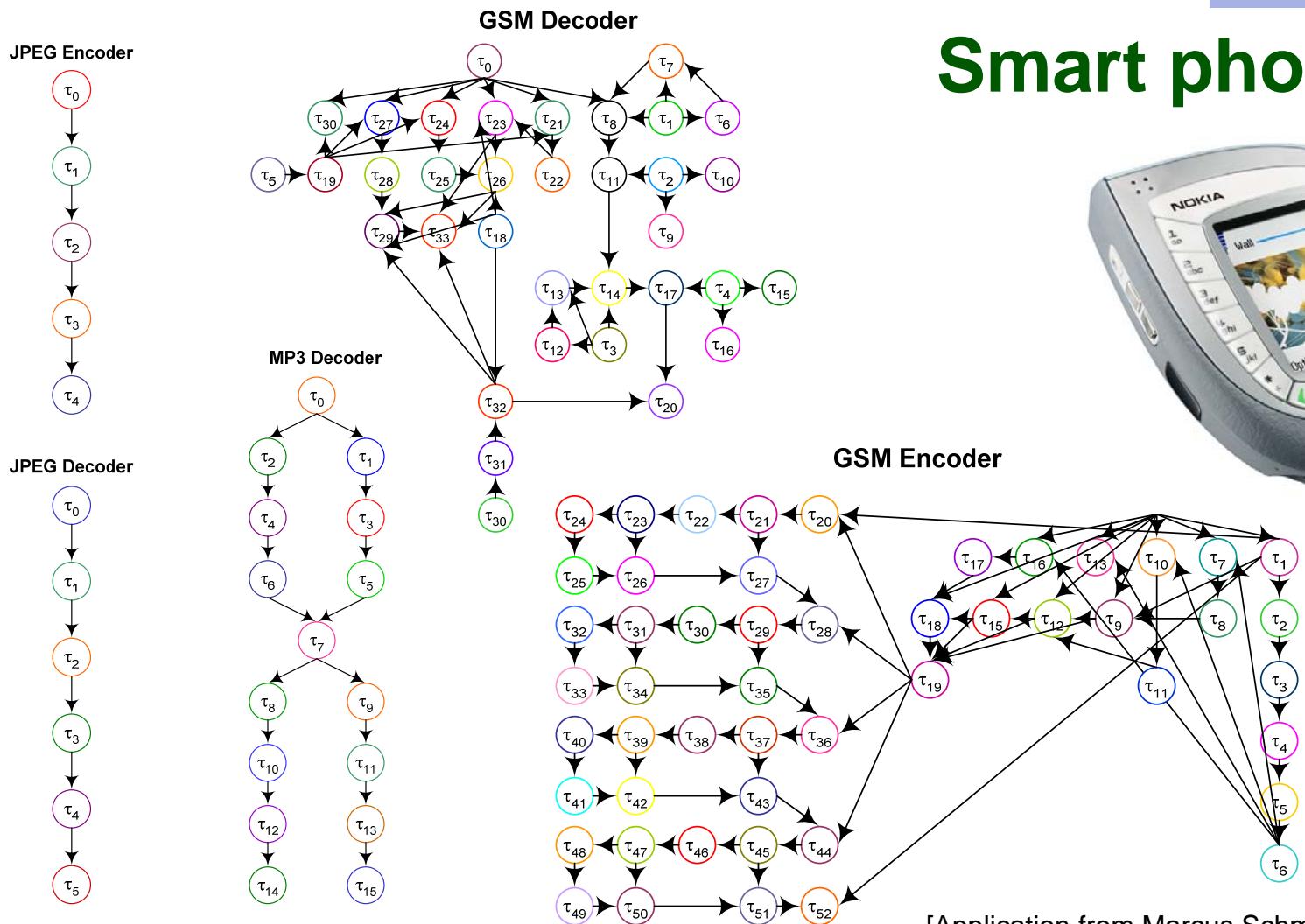


Handling Realistic Applications?

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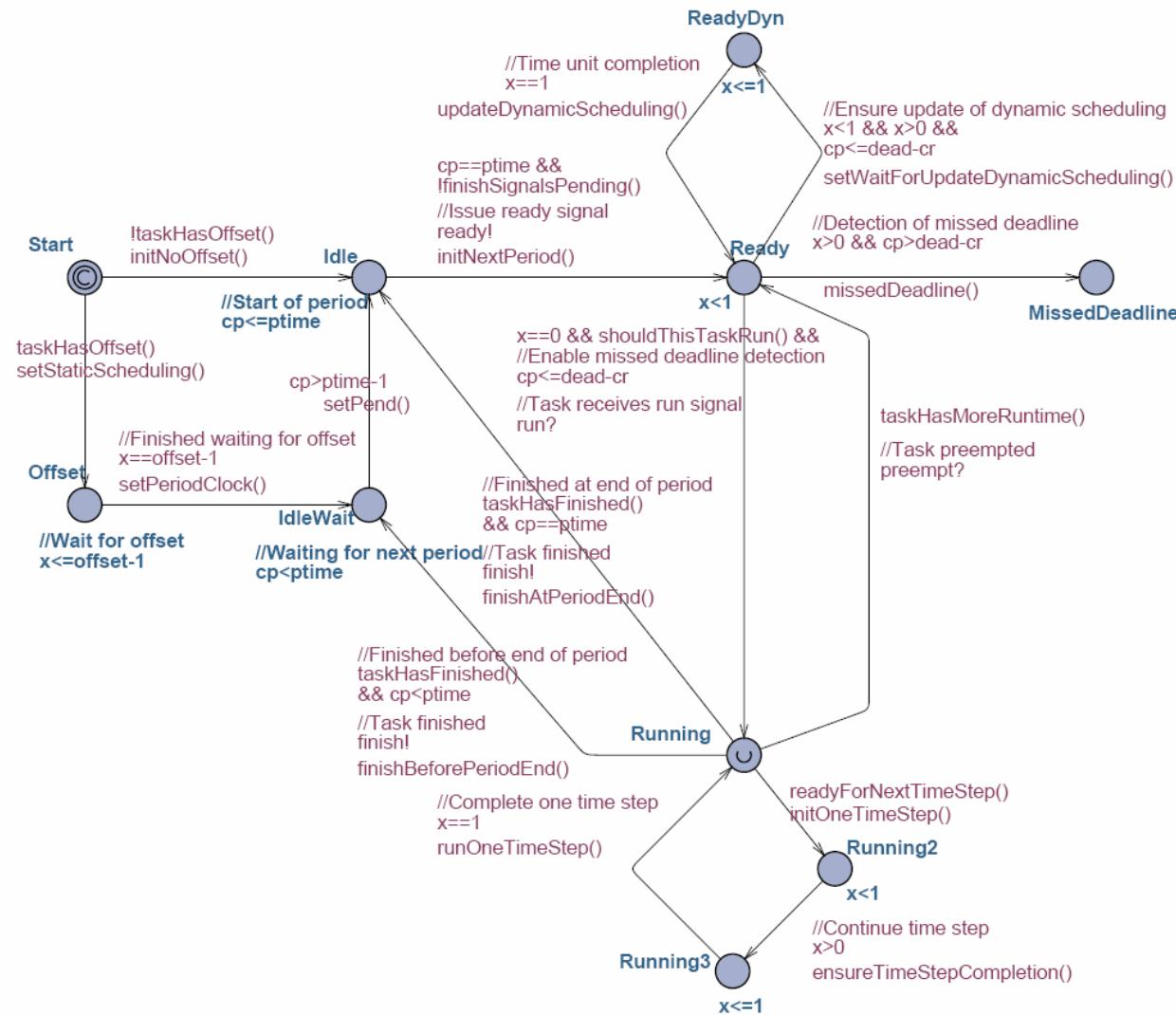
Jan Madsen / DTU

Smart phone:

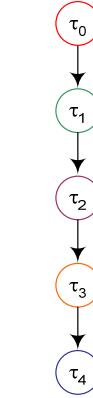


[Application from Marcus Schmitz, TU Linkoping]

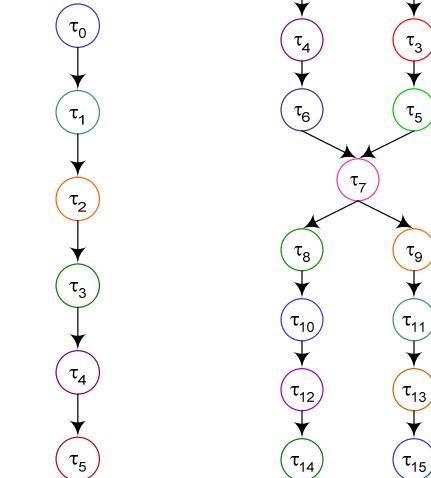
Timed Automata for a Task



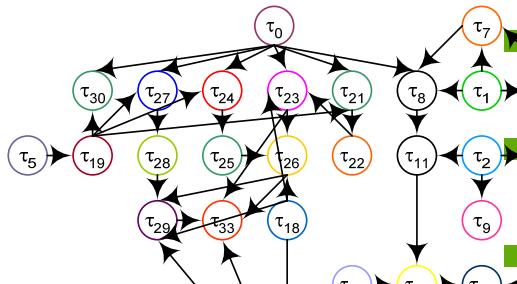
JPEG Encoder



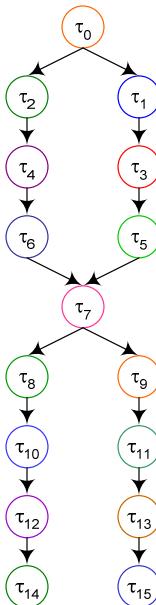
JPEG Decoder



GSM Decoder



MP3 Decoder



Tasks: 114

Deadlines: [0.02: 0.5] sec

Execution: [52 : 266.687]
cycles

Platform:

3 processors, 25 MHz

1 bus

verified in 1.5 hours!

Simulation

- CoFluent Studio
- Mentor Graphics Catapult
- SystemC
- ARTS
- Matlab/Simulink
- TrueTime
- Ptolemy

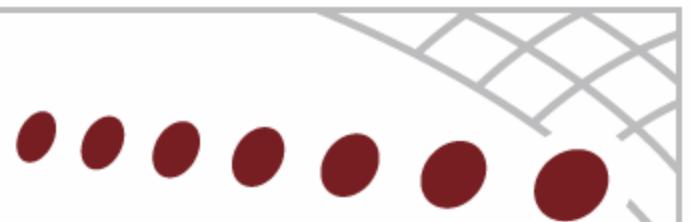
Analysis

- Esterel Studio
- AbsInt
- SymTA
- UPPAAL
- Design Trotter
- TIMES



DaNES

Danish Network for Intelligent Embedded Systems



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[\[Wednesday, 20th February.
ARTISTDesign Kick-off\]](#)

DaNES is heavily involved in ARTIST Design with CISS coordinating the activities on Modelling and Validation and DTU coordinating the activities on Hardware Platform and MPSoC Design.

The kick-off meeting of the new European Network of Excellence ARTIST Design was held in Paris on January 29 and 30, 2008.

[Read more](#)

[\[Wednesday, 20th February.
Jan Madsen on ARTEMIS board\]](#)

Professor Jan Madsen,



DaNES is a consortium - read about the partners here.



www.danes.aau.dk

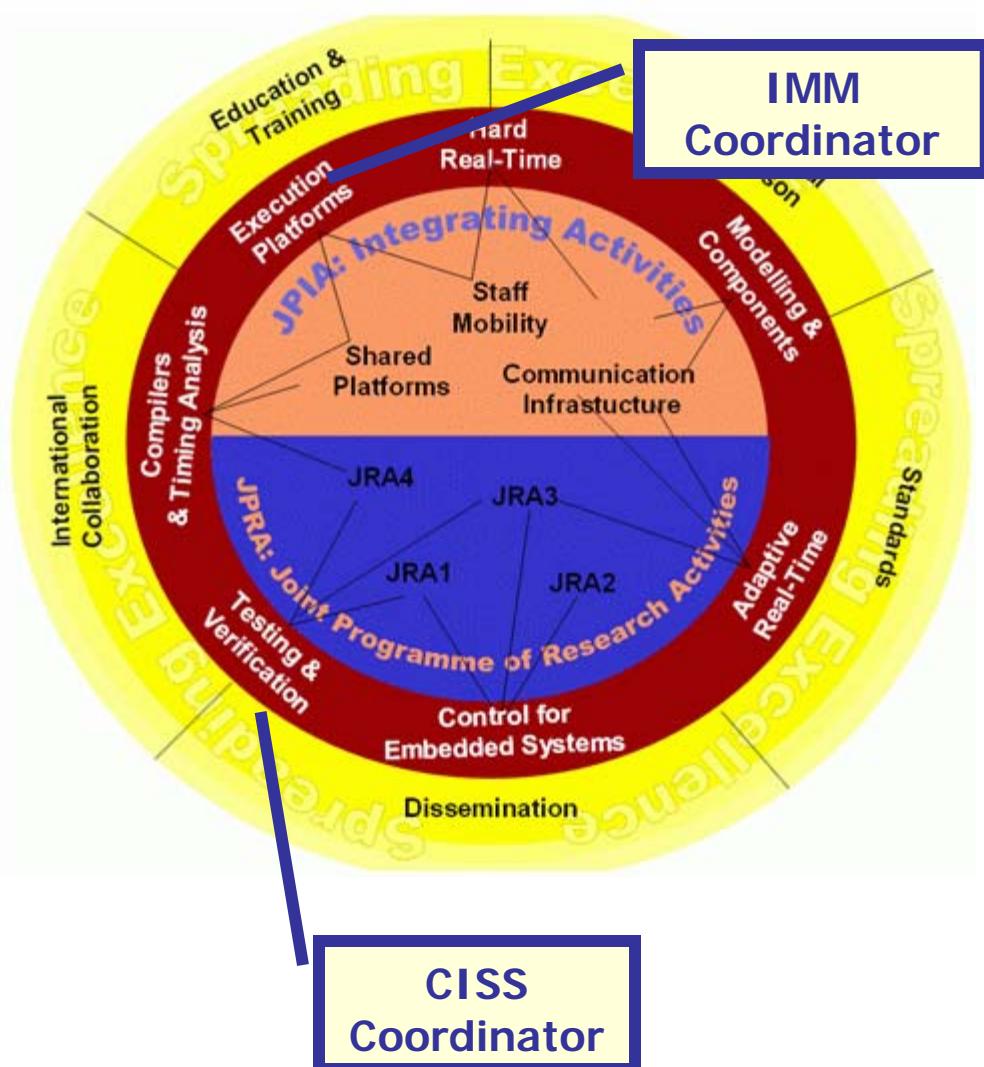
You are now logged in as **Kim Guldstrand Larsen**.
[Logout](#)

Novo Nordisk teams up with CISS: UppAAL modelling reveals protocol deficiencies

Pursuing a DaNES activity, a communication protocol for a medical device was modelled and analyzed using UppAAL, revealing protocol deficiencies. Pending specification.



Network of Excellence

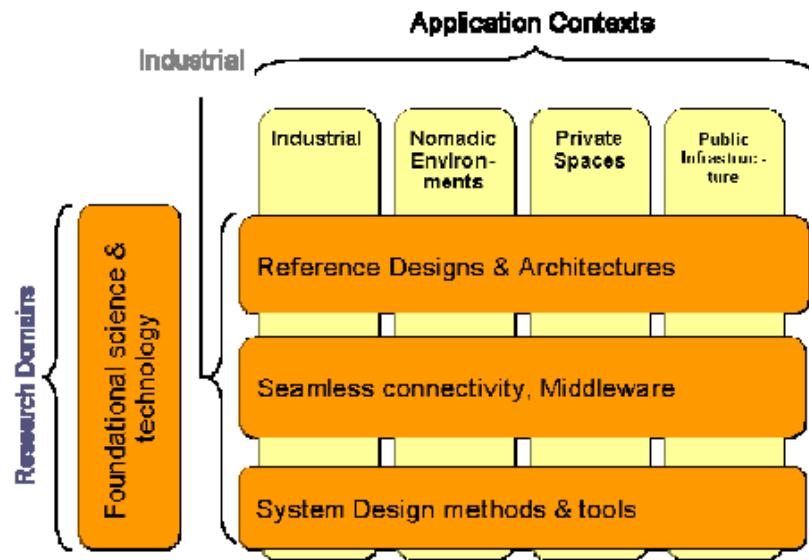


32 akademiske partners

Affiliated companies:

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Airbus
Daimler Chrysler AG
Electricite de France
Ericsson Mobile Platforms
ESA
Honeywell
Israel Aircraft
Nokia Denmark
Siemens MP
STMicroelectronics
Sun Microsystems
Thales
Volkswagen AG
Volvo Car





SP1: Metoder og processer inden for sikkerhedskritiske indlejrede systemer.

SP2: Personcentreret helbredshåndtering.

SP3: Smarte omgivelser og skalerbare digitale services.

SP4: Effektiv produktion og logistik.

SP5: Programomgivelser for indlejrede systemer.

SP6: Sikkerhed (security), privathed og pålidelighed.

SP7: Indlejret teknologi for bæredygtigt byliv.

SP8: Menneskecentreret design af indlejrede systemer.



- Deltagelse i ARTEMIS governing board
- Påvirkning af strategisk forskningsplan gennem ARTEMISIA og ARTIST
- Matchmaking på nationalt plan
- Matchmaking på internationalt plan
- Synliggørelse af calls.
- Koordinering af ansøgninger.



Thank you!
kgl@ciis.dk
www.ciis.dk